



**Robotics Hands: A Way Forward for Intelligent
And Skillful Manipulation: A Foreword By:
Professor Kevin Warwick. Professor of
Cybernetics Reading University, UK.**

Ebrahim A. Mattar

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Robotics dexterous manipulation with a number fingers has witnessed a number of developments. Hand dexterous manipulation is a difficult task, this due to a number of axioms, the first is related to complex mechanics of motion, while the last is related to the inter-related topics of intelligence and cognitive sciences needed to achieve tasks. This book is projecting fundamental topics related to dexterous Multifinger robotics manipulation. The book is summarizing large number of scientists and researchers efforts over years to assemble robotics hands with high level of dexterity, mobility, and adequate manipulability needs. Over years, there are large number of hand design attempts, some of which have been designed with high level of dexterities. Actuation and sensing have been cumbersome to achieve full skillful abilities for better manipulation. There have been some recent efforts to make use of artificial muscle type for hands actuation. Hands with artificial muscles for actuations is a new venue within robotics hands. Electroactive polymers have emerged with great promise and enabled the improvement of unique mechanisms that are biologically inspired.

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